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2015 International Symposium on Display Holography
(ISDH2015)

Image Formation of Hologram Reconstruction by Liquid Crystal on Silicon Device

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St. Petersburg, Russia // June 28-July 3, 2015

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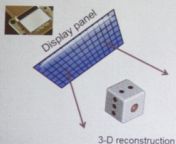
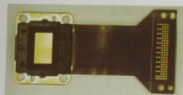
OUTLINE

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 - Holographic film vs SLM
 - SLM pixel size and viewing angle
- Image Formation and Properties
 - SLM-based Holographic display
 - SLM device structure
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 - Phase modulation of LCoS device
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Introduction

– Technical performance of SLM device

Basic structure of SLM device



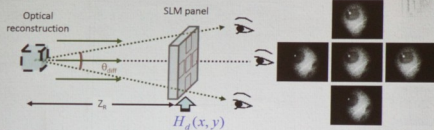
Holographic film v.s. SLM

Technical data	Holographic film	SLM
Imaging process	Wet/Dry-chemical process	Electro-optical conversion
Display type	Transmission/Reflection	Transmission/Reflection
Display area	> 50 × 60 cm ²	1.5 × 0.7 cm ²
Resolution	> 3,000 lps/mm	6.4 μm (3.74 μm)*
Structure	Continues	Pixelated
Operation	Static	Dynamic & Reconfigurable

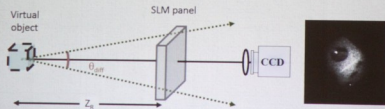
Introduction

= SLM pixel size and viewing angle

- Optical reconstruction of digital/computer hologram

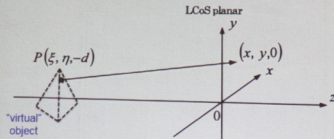


- Optical reconstruction for 3-D virtual image



Wavelength(λ): 532 nm Pixel size(Δx): 6.4 μm Viewing angle: $2\theta_{off\text{ max}} = 2 \sin^{-1} \left(\frac{\lambda}{2\Delta x} \right) \approx 5^\circ$

SLM-based holographic display – Phase hologram



Coordinate for LCoS-based holographic display

◆ Phase hologram formation

- Diffracted light of "virtual object" pass through SLM-based holographic display system
- Light field formed by a point source P of the "virtual object", in the plane $z=0$

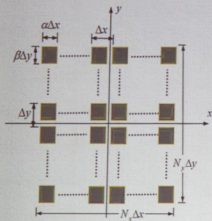
$$u_i(x, y, z, \eta) = \frac{\exp(jkz)}{j\lambda d} \iint_{-\infty}^{\infty} \delta(x_i - \xi, y_i - \eta) \exp\left\{ \frac{jk}{2d} [x - x_i]^2 + (y - y_i)^2 \right\} dx_i dy_i$$

- The expression of a phase hologram with unitary amplitude

$$u_o(x, y, z, \eta) = \frac{\exp(jkz)}{j} \exp\left\{ \frac{jk}{2d} [x - \xi]^2 + (y - \eta)^2 \right\} \quad \rightarrow \text{Phase hologram on LCoS device}$$

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SLM-based holographic display – Image formation and properties



Device structure and coordinate definitions

- The phase hologram formed in LCoS

$$H_s(x, y, \xi, \eta) = u'_s(x, y, \xi, \eta) w(x, y)$$

- The window function of SLM device

Aperture of the SLM

$$w(x, y) = \text{rect}\left(\frac{x}{N_x \Delta x}\right) w_s(x) \text{rect}\left(\frac{y}{N_y \Delta y}\right) w_p(y)$$

Pixel of the SLM

$$\begin{cases} w_s(x) = \left[\text{rect}\left(\frac{x}{\alpha \Delta x}\right) * \text{comb}\left(\frac{x - \Delta x / 2}{\Delta x}\right) \right] \\ w_p(y) = \left[\text{rect}\left(\frac{y}{\beta \Delta y}\right) * \text{comb}\left(\frac{y - \Delta y / 2}{\Delta y}\right) \right] \end{cases}$$

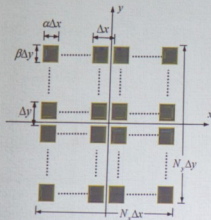
- Image formation and properties

- LCoS parameters
- Pixel number (N_x, N_y), pixel size (Δ_x, Δ_y), and fill factor (α, β)

[Ref] J. Li, H. Y. Tu, W. C. Yeh, J. Gui, and C. J. Cheng, Appl. Opt. 53(27), G222-G231 (2014).

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SLM-based holographic display – Impulse response



device structure and coordinate definitions

[Ref] J. Li, H. Y. Tu, W. C. Yeh, J. Gui, and C. J. Cheng, Appl Opt. 53(7), G222-G231 (2014).

- According to the Fourier optics, the reconstructed image in the Fresnel plane is

$$h_1(x, y; \xi, \eta) = \frac{1}{jd} \exp\left[\frac{jk}{2d}(\xi^2 + \eta^2)\right] \times \exp\left[-\frac{jk}{2d}(x' + y')\right] \mathcal{F}^{-1}\{w(x, y)\}$$

- A simplified result in the case of the zero diffracted order

$$h_0(x, y; \xi, \eta) = \frac{1}{jd} \alpha \beta N_x N_y \Delta x \Delta y \text{sinc}(\alpha/2)$$

$$\square \text{sinc}(\beta/2) \text{sinc}\left[\frac{N_x \Delta x}{jd} \left(x - \xi - \frac{jd}{2\Delta x}\right)\right]$$

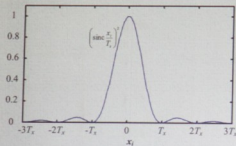
$$\square \text{sinc}\left[\frac{N_y \Delta y}{jd} \left(y - \eta - \frac{jd}{2\Delta y}\right)\right]$$

- The reconstructed image
 - Modulated by sinc function of SLM array size (Large array size for high quality reconstruction)
 - 3-D object can be considered as a collection of many point sources in space, so this analysis method can be applied to 3D reconstruction

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SLM-based holographic display = Depth of focus

The depth of focus as a function of $[\text{sinc}(x_i/T_x)]^2$



Recording configuration:

Wavelength (λ): 532 nm

Pixel number (N_x): 1024

Pixel size (Δx): 6.4 μm

Diffraction distance (d):

$d = 400 \text{ mm}$

$d_s = 3.96 \text{ mm}$

$d = 1200 \text{ mm}$

$d_s = 35.67 \text{ mm}$

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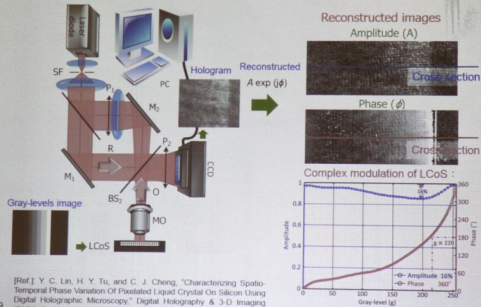
- The reconstruction distance $d' \neq d$
- The light intensity distribution at image plane is proportional to $[\text{sinc}(x_i/T_x)\text{sinc}(y_i/T_y)]^2$

$$2T = 2T_x = 2 \frac{\lambda d}{N_x \Delta x} = \left| \frac{d-d'}{d} \right| N_x \Delta x$$

➔ Depth of focus: $d_s \approx \frac{2\lambda d^2}{(N_x \Delta x)^2}$

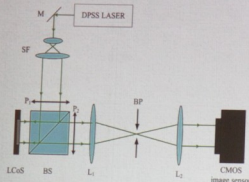
- The depth of focus depend on diffraction distance and device parameters
- A long diffraction distance has large depth of focus
- 3D reconstruction image can be resolved in the depth of focus

Experiments - Phase modulation of LCoS device



[Ref.] Y. C. Lin, H. Y. Tu, and C. J. Cheng, "Characterizing Spatio-Temporal Phase Variation Of Pixelated Liquid Crystal On Silicon Using Digital Holographic Microscopy," Digital Holography & 3-D Imaging (DH2015), Shanghai, China, May 24-28, 2015.

Experiments — Setup and Procedure



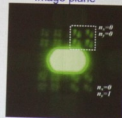
Experimental setup of the LCoS-based holographic display

- Light source : DPSS Laser
(wavelength: 532 nm)
- SLM: liquid crystal on silicon device (LCoS)
(1920X1080, 6.4 μm)
- Focal length of Lens: 300 mm (L_1)
150 mm (L_2)
- CMOS sensor: 2560X1920, 2.2 μm BP: band-pass filter

Optical reconstruction
Spatial frequency plane



Image plane

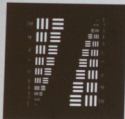


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Experimental - Spatial resolution

results

Target to be recorded



Line pairs of "virtual" object

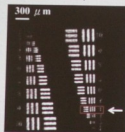
Number	1	2	3	4	5	6	7	8	9	10
Line Pairs / mm	78.1	39.1	26.0	19.5	15.6	13.0	11.7	9.8	8.7	7.8
Line width (μm)	6.4	12.8	19.2	25.6	32.0	38.4	44.8	51.2	57.6	64.0

Reconstruction image:

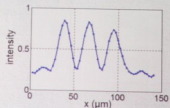
- Reconstruction distance (d_r): 263 mm
- Depth of focus (d_s): 1.4 mm
- Spatial resolution: $23 \mu\text{m}$ (theoretical)

Optical reconstruction image

Reconstruction plane

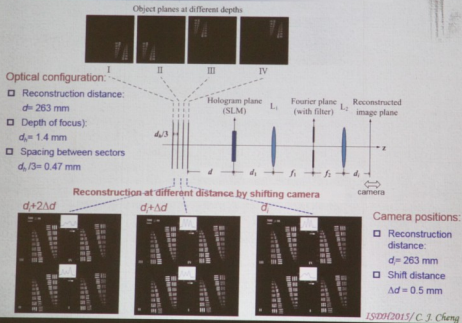


Cross-section profile at "line pair 4"



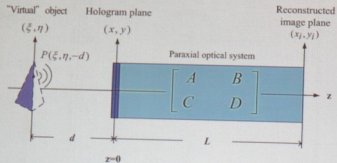
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Experimental results — Depth of focus



Potential Applications

– SLM-based holographic display with paraxial optical system



- Ray matrix optics and scalar diffraction theory can be applied to SLM-based holographic display architecture combining with paraxial optical systems.
- Paraxial optical system can be a telescopic imaging, 4-f processing system et al.
- The image formation and properties can be also obtained by the proposal method.

[Ref.] J. Li, Y. C. Lin, H. Y. Tu, J. Gu, C. Li, Y. Lou, and C. J. Cheng, "Image Formation of Holographic Three-dimensional Display Based on Spatial Light Modulator in Paraxial Optical Systems," *J. Micro/Nanolithography, MEMS, and MOEM*, 2015 (in press)

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Summary

- This work describes the image formation and properties of the SLM-based holographic 3D display.
- The impulse response and the depth of focus of hologram reconstruction depend on both optical configuration and SLM device structure.
- This approach can be applied to analyze a more general case of SLM-based holographic display with paraxial optical system.



Thank you for your attention

Collaboration work

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