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A fast occlusion effect calculation method by multi-view inverse orthographic projection in 3D holographic display

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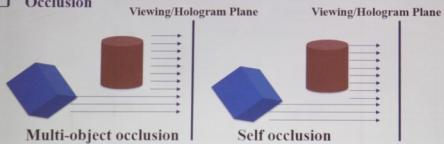
01-July-2015 Saint-Petersburg, Russia

Outline

- Introduction
- Occlusion culling using inverse orthographic projection
- Design of the angular sampling pitch
- Implement and results
- Conclusion

Introduction

❑ Occlusion



❑ Occlusion culling

- Computation load reduction
- Crosstalk reduction
- Correct depth cues production (motion depth cues)

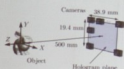


Left view point ——— Right view point

Introduction

❑ Occlusion culling methods

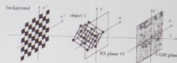
- Based on Ray light
 - Holographic stereogram
 - Multi projection
- Based on Extra samplings
 - Mask based
 - Ray-tracing
- Others
 - Ray-wave conversion



Multi projection



Ray tracing



Ray-wave conversion

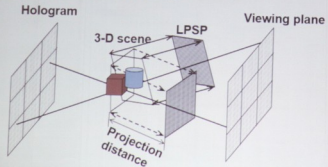
❑ The limitation

- Limited to reconstructed deep scene with continue depth
- No accommodation cue
- Heavy computational load
- Poor quality of reconstructed image for deep scene

Rick H.-Y. Chen, Appl. Opt. 48, 4246-4255 (2009)
Koki Wakunami, Opt. Express 21, 21811-21822 (2013)

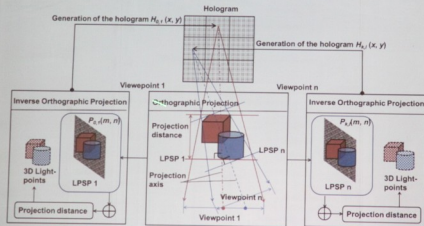
Occlusion culling using inverse orthographic projection

- The principle of our occlusion culling method
 - Step 1: The multiple light point sampling planes are used to remove the hidden surface for each direction of views.
 - Step 2: Inverse orthographic projection is used to obtain the 3D points in real 3D space without any distortion.
 - Step 3: The sub holograms are calculated by the corresponding 3D light points based on wave front.



Occlusion culling using inverse orthographic projection

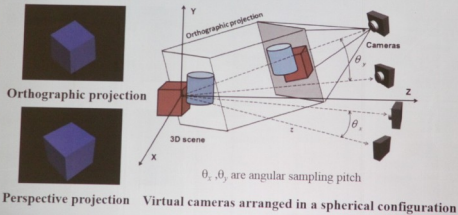
□ Occlusion culling of multi objects



$$H_{x,j}(x, y) = \sum_{m,n=0}^{M-1, N-1} A_{k,j}(m, n) \exp\left[i \frac{2\pi}{\lambda} r_{k,j}(m, n)\right] \exp(i\phi_{m,n}) \quad \text{Holo}(p, q) = H_{x,j}\left(p - k \times \frac{x_j}{\Delta u}, q - l \times \frac{y_j}{\Delta u}\right)$$

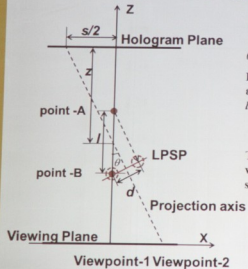
Occlusion culling using inverse orthographic projection

- Performance of the orthographic projection process by virtual cameras arranged in a spherical configuration.



Occlusion culling using inverse orthographic projection

□ Designed of angular sampling pitch



$$\theta = \arcsin\left(\frac{2D \tan(\epsilon/2)}{l}\right)$$

D: the observe distance

ϵ : the resolution of human eyes

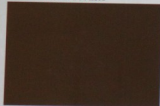
l: the distance between two object points

The angular sampling pitch will be large when reconstructing 3D objects with smooth surfaces or shallow depths.

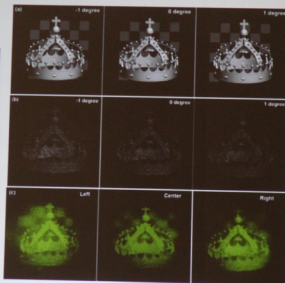
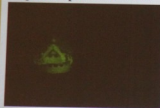
Implement and results

Occlusion effect

Simulation results

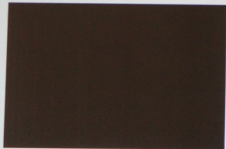
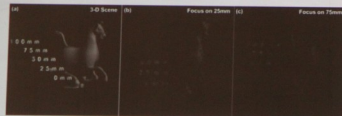


Optical experiment results



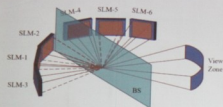
Implement and results

- Reconstruction of a deep 3D scene with continuous depth



Implement and results

Experimental system



Spatial light modulators (SLM)
Holoeye Pluto
Resolution: 1920×1080
Pixel pitch: 8 μ m
Screen size: 15.36mm \times 8.64mm
Viewing zone angle: 22.8 degree

Conclusion

- ❑ A fast occlusion effect calculation method is proposed by multi-view inverse orthographic projection in 3D holographic display.
- ❑ The reduced angular sampling method is proposed using the advantage of the limitation of human eyes.
- ❑ The experimental system is built up by tiling 6 SLMs, and 22.8 viewing angle is obtained.



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Thanks for your attention!



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